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Abdulrasheed Bello Badawaire

Department of Mathematics and Statistics, Federal University Wukari, Wukari, Nigeria

Issam Dawoud

Department of Mathematics, Al-Aqsa University, Gaza, Palestine

Adewale Folaranmi Lukman

Department of Mathematics, University of Medical Sciences, Ondo, Nigeria

Victoria Laoye

Department of Statistics, University of Ibadan, Ibadan, Nigeria

Arowolo Olatunji

Department of Mathematical Sciences, Lagos State University of Science and Technology, Lagos, Nigeria.

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ORIGINAL STUDY

Biassing Estimator to Mitigate Multicollinearity in Linear Regression Model

Abdulrasheed Bello Badawaire ^{a,*}, Issam Dawoud ^b, Adewale F. Lukman ^c,
Victoria Laoye ^d, Arowolo Olatunji ^e

^a Department of Mathematics and Statistics, Federal University Wukari, Wukari, Nigeria

^b Department of Mathematics, Al-Aqsa University, Gaza, Palestine

^c Department of Mathematics, University of Medical Sciences, Ondo, Nigeria

^d Department of Statistics, University of Ibadan, Ibadan, Nigeria

^e Department of Mathematical Sciences, Lagos State University of Science and Technology, Lagos, Nigeria

Abstract

A new two-parameter estimator was developed to combat the threat of multicollinearity for the linear regression model. Some necessary and sufficient conditions for the dominance of the proposed estimator over ordinary least squares (OLS) estimator, ridge regression estimator, Liu estimator, KL estimator, and some two-parameter estimators are obtained in the matrix mean square error sense. Theory and simulation results show that, under some conditions, the proposed two-parameter estimator consistently dominates other estimators considered in this study. The real-life application result follows suit.

Mathematics Subject Classification: 62J05, 62J07

Keywords: Liu estimator, MSE, Multicollinearity, Ridge regression, Simulation study

1. Introduction

We consider the following linear regression model:

$$y = X\beta + \varepsilon, \quad (1)$$

where $y_{n \times 1}$ vector of the response variable, $X_{n \times p}$ matrix of explanatory variables, $\beta_{p \times 1}$ vector of regression parameters, $\varepsilon_{n \times 1}$ vector of errors ($E(\varepsilon) = 0$, $V(\varepsilon) = \sigma^2 I_n$, and I_n identity matrix). The ordinary least squares estimator (OLSE) of β is

$$\hat{\beta} = S^{-1}X'y \quad (2)$$

where $S = X'X$.

The OLSE performs poorly when the explanatory variables in the linear regression model (LRM) are collinear. Collinearity arises when there exists a linear relationship among the explanatory variables.

In that case, it becomes difficult to make a valid inference about the regression parameters of the model. Several estimators have been suggested as alternatives to the OLSE to handle the threat of multicollinearity as [1,2,11,12,19,20,22,27–32,34,36], (B. M. [15], (B. M [15], [8], (S [6,38].

In some situations, a linear relationship between predictors and other assumption violations can jointly occur. Researchers such as [20,22,33] proposed various Ridge-type M-Estimators that jointly combat the problem of multicollinearity and outliers in Y-direction. Also [3,7], suggested some method of parameter estimation in the linear regression model when multicollinearity and outliers are jointly present [24]. Proposed a Ridge-type estimator for the Gamma regression to handle the problem of multicollinearity when the response variable is right-skewed [39]. Proposed a two-stage K-L estimator that handled both multicollinearity and autocorrelation. In some real-life scenarios, predicting the

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* Corresponding author.

E-mail addresses: abdulrasheed@fuwukari.edu.ng (A.B. Badawaire), fadewale@unimed.edu.ng (A.F. Lukman), laoyevictoria@gmail.com (V. Laoye), arowolo.ot@lasustech.edu.ng (A. Olatunji).

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current values of a dependent variable based on the current values of a predictor when the explanatory variables are correlated with their lagged values yield unreliable results. To overcome this challenge [25], proposed the Almon-KL estimator (A-KLE).

We developed a new two-parameter estimator for parameter estimation in the LRM in this study and compared its performance with some existing ones. We will give very brief descriptions of these existing estimators in the following subsections.

1.1. Some alternative biased estimators

One of the most popular estimators dealing with multicollinearity is the ordinary ridge regression (ORR) estimator which was proposed by [11] and is defined as

$$\hat{\beta}_k = W \hat{\beta}, \quad k \geq 0 \quad (3)$$

where $W = (I_p + k S^{-1})^{-1}$ and k is the biasing parameter.

The other alternative biased estimator for dealing with multicollinearity is the Liu estimator defined by [12] as

$$\hat{\beta}_d = F_d \hat{\beta}, \quad 0 < d < 1 \quad (4)$$

where $F_d = (S + I_p)^{-1}(S + d I_p)$ and d is the biasing parameter.

Ozkale and Kaciranlar (2007) proposed the two-parameter estimator and is defined as

$$\hat{\beta}_{kd} = R_{kd} \hat{\beta}, \quad k \geq 0, 0 < d < 1 \quad (5)$$

where $R_{kd} = (S + k I_p)^{-1}(S + k d I_p)$.

Then [36], proposed another two-parameter estimator based on the Liu estimator and the ORR estimator, and is defined as

$$\hat{\beta}(k, d) = F_d W \hat{\beta}, \quad k \geq 0, 0 < d < 1 \quad (6)$$

And recently, (B. M. [15]), proposed a one-parameter estimator called Kibria-Lukman estimator and defined as,

$$\hat{\beta}_{KL} = W M \hat{\beta}, \quad k \geq 0 \quad (7)$$

where $M = (I_p - k S^{-1})$.

1.2. The new two-parameter estimator

The new estimator is obtained by replacing $\hat{\beta}$ with $\hat{\beta}_{KL}$ in the Liu estimator and becomes as follows:

$$\hat{\beta}_{proposed} = F_d W M \hat{\beta}, \quad k \geq 0, 0 < d < 1 \quad (8)$$

The properties of the estimator are as follows:

$$E(\hat{\beta}_{proposed}) = F_d W M E(\hat{\beta}) = F_d W M \beta. \quad (9)$$

$$B(\hat{\beta}_{proposed}) = [F_d W M - I_p] \beta. \quad (10)$$

$$D(\hat{\beta}_{proposed}) = \sigma^2 F_d W M S^{-1} M' W' F_d' \quad (11)$$

and the matrix mean squared error (MSEM) is

$$MSEM(\hat{\beta}_{proposed}) = \sigma^2 F_d W M S^{-1} M' W' F_d' + [F_d W M - I_p] \beta \beta' [F_d W M - I_p]' \quad (12)$$

We rewrite (1) in the canonical form as follows:

$$y = Z\alpha + \varepsilon, \quad (13)$$

where $Z = X \tilde{Q}$ and $\alpha = \tilde{Q}' \beta$. $\tilde{Q}$ is an orthogonal matrix such that $Z' Z = \tilde{Q}' X' X \tilde{Q} = \Lambda = \text{diag}(e_1, e_2, \dots, e_p)$.

Then the OLS estimator of α in terms of eigenvalues is obtained as follows:

$$\hat{\alpha} = \Lambda^{-1} Z' y, \quad (14)$$

with mean square error matrix (MSEM),

$$MSEM(\hat{\alpha}) = \sigma^2 \Lambda^{-1}. \quad (15)$$

The ridge regression estimator of α is

$$\hat{\alpha}(k) = W \hat{\alpha}, \quad (16)$$

where $W = [I_p + k \Lambda^{-1}]^{-1}$.

and its MSEM is

$$MSEM(\hat{\alpha}(k)) = \sigma^2 W \Lambda^{-1} W' + (W - I_p) \alpha \alpha' (W - I_p)' \quad (17)$$

where $(W - I_p) = -k(\Lambda + k I_p)^{-1}$.

The Liu estimator of α is

$$\hat{\alpha}(d) = F_d \hat{\alpha}, \quad (18)$$

where $F_d = [\Lambda + I_p]^{-1}[\Lambda + d I_p]$.

and its MSEM is

$$MSEM(\hat{\alpha}(d)) = \sigma^2 F_d \Lambda^{-1} F_d' + (1 - d)^2 (\Lambda + I_p)^{-1} \alpha \alpha' (\Lambda + I_p)^{-1} \quad (19)$$

The Ozkale and Kaciranlar estimator of α is

$$\hat{\alpha}_{kd} = R_{kd} \hat{\alpha}, \quad (20)$$

where $R_{kd} = [\Lambda + k I_p]^{-1}[\Lambda + k d I_p]$.

$$MSEM(\hat{\alpha}_{kd}) = \sigma^2 R_{kd} \Lambda^{-1} R_{kd}' + [R_{kd} - I_p] \alpha \alpha' [R_{kd} - I_p]' \quad (21)$$

The Yang and Chang estimator of α is

$$\hat{\alpha}(k, d) = F_d W \hat{\alpha} \quad (22)$$

$$MSEM(\hat{\alpha}(k, d)) = \sigma^2 F_d W \Lambda^{-1} W' F_d' + [F_d W - I_p] \alpha \alpha' [F_d W - I_p]' \quad (23)$$

The KL estimator of α is

$$\hat{\alpha}_{KL} = W M \hat{\alpha}, \quad (24)$$

where $M = [I_p - k \Lambda^{-1}]$
and its MSE is

$$MSEM(\hat{\beta}_{KL}) = \sigma^2 W M \Lambda^{-1} M' W' + [W M - I_p] \alpha \alpha' [W M - I_p]' \quad (25)$$

The Proposed estimator of α is

$$\hat{\alpha}_{proposed} = F_d W M \hat{\alpha}, \quad (26)$$

and its MSEM is,

$$MSEM(\hat{\beta}_{proposed}) = \sigma^2 F_d W M \Lambda^{-1} M' W' F_d' + [F_d W M - I_p] \alpha \alpha' [F_d W M - I_p]' \quad (27)$$

The following lemma is used to make some theoretical comparison among estimators in the section follow.

Lemma 1: Let $\hat{\beta}_1$ and $\hat{\beta}_2$ be two linear estimators of $\tilde{\beta}$. The difference in the covariance of the two estimators D is positive definite (pd) if and only if $bias(\hat{\beta}_2)' [\sigma^2 \tilde{D} + bias(\hat{\beta}_1) bias(\hat{\beta}_1)']^{-1} bias(\hat{\beta}_2) < 1$.

Consequently,

$$MSEM(\hat{\beta}_1) - MSEM(\hat{\beta}_2) = \sigma^2 D + bias(\hat{\beta}_1) bias(\hat{\beta}_1)' - bias(\hat{\beta}_2) bias(\hat{\beta}_1)' > 0 \quad [35].$$

2. Comparison among the estimators

2.1. $\hat{\alpha}$ and $\hat{\alpha}_{proposed}$

Theorem 2.1: $\hat{\alpha}_{proposed}$ dominates $\hat{\alpha}$ if and only if

$$\alpha' [F_d W M - I_p]' [\sigma^2 (\Lambda^{-1} - F_d W M \Lambda^{-1} M' W' F_d')] \times [F_d W M - I_p] \alpha < 1 \quad (28)$$

Proof:

$$D(\hat{\alpha}) - D(\hat{\alpha}_{proposed}) = \sigma^2 (\Lambda^{-1} - F_d W M \Lambda^{-1} M' W' F_d') = \sigma^2 \text{diag} \left\{ \frac{1}{e_i} - \frac{(e_i + d)^2 (e_i - k)^2}{e_i (e_i + 1)^2 (e_i + k)^2} \right\}_{i=1}^p \quad (29)$$

where $\Lambda^{-1} - \sigma^2 F_d W M \Lambda^{-1} M' W' F_d'$ is pd since $(e_i + 1)(e_i + k) - (e_i + d)(e_i - k) > 0$.

Consequently, $\Lambda^{-1} - F_d W M \Lambda^{-1} M' W' F_d'$ is pd.

2.1. $\hat{\alpha}(k)$ and $\hat{\alpha}_{proposed}$

Theorem 2.2: $\hat{\alpha}_{proposed}$ dominates $\hat{\alpha}(k)$ if and only if

$$\alpha' [F_d W M - I_p]' [V_1 + [W - I_p] \alpha \alpha' [W - I_p]'] \times [F_d W M - I_p] \alpha < 1 \quad (30)$$

where $V_1 = \sigma^2 (W \Lambda^{-1} W' - F_d W M \Lambda^{-1} M' W' F_d')$

Proof:

$$V_1 = \sigma^2 (W \Lambda^{-1} W' - F_d W M \Lambda^{-1} M' W' F_d') = \sigma^2 \text{diag} \left\{ \frac{e_i}{(e_i + k)^2} - \frac{(e_i + d)^2 (e_i - k)^2}{e_i (e_i + 1)^2 (e_i + k)^2} \right\}_{i=1}^p \quad (31)$$

where $W \Lambda^{-1} W' - F_d W M \Lambda^{-1} M' W' F_d'$ is pd since $e_i (k + 1 - d) + kd > 0$.

2.3. $\hat{\alpha}(d)$ and $\hat{\alpha}_{proposed}$

Theorem 2.3: $\hat{\alpha}_{proposed}$ dominates $\hat{\alpha}(d)$ if and only if

$$\alpha' [F_d W M - I_p]' [V_2 + [F_d - I_p] \alpha \alpha' [F_d - I_p]'] [F_d W M - I_p] \alpha < 1 \quad (32)$$

where $V_2 = \sigma^2 (F_d \Lambda^{-1} F_d' - F_d W M \Lambda^{-1} M' W' F_d')$

Proof: The difference between the dispersion matrices is

$$V_2 = \sigma^2 (F_d \Lambda^{-1} F_d' - F_d W M \Lambda^{-1} M' W' F_d') = \sigma^2 \text{diag} \left\{ \frac{(e_i + d)^2}{e_i (e_i + 1)^2} - \frac{(e_i + d)^2 (e_i - k)^2}{e_i (e_i + 1)^2 (e_i + k)^2} \right\}_{i=1}^p \quad (33)$$

where $F_d \Lambda^{-1} F_d' - F_d W M \Lambda^{-1} M' W' F_d'$ is pd since $(e_i + k) - (e_i - k) = 2k > 0$.

2.4. $\hat{\alpha}_{KL}$ and $\hat{\alpha}_{proposed}$

Theorem 2.4: $\hat{\alpha}_{proposed}$ dominates $\hat{\alpha}_{KL}$ if and only if

$$\alpha' [F_d W M - I_p]' [V_3 + [W M - I_p] \alpha \alpha' [W M - I_p]'] \times [F_d W M - I_p] \alpha < 1 \quad (34)$$

where $V_3 = \sigma^2 (W M \Lambda^{-1} M' W' - F_d W M \Lambda^{-1} M' W' F_d')$

Proof:

$$V_3 = \sigma^2 (W M \Lambda^{-1} M' W' - F_d W M \Lambda^{-1} M' W' F_d') = \sigma^2 \text{diag} \left\{ \frac{(e_i - k)^2}{e_i (e_i + k)^2} - \frac{(e_i + d)^2 (e_i - k)^2}{e_i (e_i + 1)^2 (e_i + k)^2} \right\}_{i=1}^p \quad (35)$$

where $W M \Lambda^{-1} M' W' - F_d W M \Lambda^{-1} M' W' F_d'$ is pd since $(e_i + 1) - (e_i + d) = 1 - d > 0$.

2.5. $\hat{\alpha}_{kd}$ and $\hat{\alpha}_{proposed}$

Theorem 2.5: $\hat{\alpha}_{proposed}$ dominates $\hat{\alpha}_{kd}$ if and only if

$$\alpha' [F_d W M - I_p]' [V_4 + [R_{kd} - I_p] \alpha \alpha' [R_{kd} - I_p]'] [F_d W M - I_p] \alpha < 1 \quad (36)$$

where $V_4 = \sigma^2 (R_{kd} \Lambda^{-1} R_{kd}' - F_d W M \Lambda^{-1} M' W' F_d')$

Proof:

$$V_4 = \sigma^2 (R_{kd} \Lambda^{-1} R_{kd}' - F_d W M \Lambda^{-1} M' W' F_d') \\ = \sigma^2 \text{diag} \left\{ \frac{(e_i + kd)^2}{e_i (e_i + k)^2} - \frac{(e_i + d)^2 (e_i - k)^2}{e_i (e_i + 1)^2 (e_i + k)^2} \right\}_{i=1}^p \quad (37)$$

where $R_{kd} \Lambda^{-1} R_{kd}' - F_d W M \Lambda^{-1} M' W' F_d'$ is pd since $e_i (kd + k + 1 - d) + 2kd > 0$.

2.7. Determination of the parameters k and d

In determining the optimal value of k , first we assume that d is fixed [10], (B. M. G. [14], (B. M. [13], and [17]. Then the optimal value of k can be obtained by choosing k that minimize

$$MSEM(\hat{\alpha}_{proposed}) = E((\hat{\alpha}_{proposed} - \alpha)'(\hat{\alpha}_{proposed} - \alpha))$$

$$m(k, d) = \text{tr}(MSEM(\hat{\alpha}_{proposed}))$$

$$m(k, d) = \sigma^2 \sum_{i=1}^p \frac{(e_i + d)^2 (e_i - k)^2}{e_i (e_i + 1)^2 (e_i + k)^2} \\ + \sum_{i=1}^p \frac{(e_i (2k - d + 1) + k(d + 1))^2 \alpha_i^2}{(e_i + 1)^2 (e_i + k)^2} \quad (40)$$

Differentiate equation (40) with respect to k

$$\frac{\partial m(k, d)}{\partial k} = -2\sigma^2 \sum_{i=1}^p \frac{(e_i + d)^2 (e_i - k)}{e_i (e_i + 1)^2 (e_i + k)^2} - 2\sigma^2 \sum_{i=1}^p \frac{(e_i + d)^2 (e_i - k)^2}{e_i (e_i + 1)^2 (e_i + k)^3} \\ + 2(2e_i + d + 1) \sum_{i=1}^p \frac{(e_i (2k - d + 1) + k(d + 1)) \alpha_i^2}{(e_i + 1)^2 (e_i + k)^2} - 2 \sum_{i=1}^p \frac{(e_i (2k - d + 1) + k(d + 1))^2 \alpha_i^2}{(e_i + 1)^2 (e_i + k)^3} \quad (41)$$

2.6. $\hat{\alpha}(k, d)$ and $\hat{\alpha}_{proposed}$

Theorem 2.6: $\hat{\alpha}_{proposed}$ dominates $\hat{\alpha}(k, d)$ if and only if

$$\alpha' [F_d W M - I_p]' [V_5 + [F_d W - I_p] \alpha \alpha' [F_d W - I_p]'] \times [F_d W M - I_p] \alpha < 1 \quad (38)$$

where $V_5 = \sigma^2 (F_d W \Lambda^{-1} W' F_d' - F_d W M \Lambda^{-1} M' W' F_d')$

Proof:

$$V_5 = \sigma^2 (F_d W \Lambda^{-1} W' F_d' - F_d W M \Lambda^{-1} M' W' F_d') \\ = \sigma^2 \text{diag} \left\{ \frac{e_i (e_i + d)^2}{(e_i + 1)^2 (e_i + k)^2} - \frac{(e_i + d)^2 (e_i - k)^2}{e_i (e_i + 1)^2 (e_i + k)^2} \right\}_{i=1}^p \quad (39)$$

where $F_d W \Lambda^{-1} W' F_d' - F_d W M \Lambda^{-1} M' W' F_d'$ is pd since $e_i - (e_i - k) = k > 0$.

$$\frac{\partial m(k, d)}{\partial k} = 0, \text{ then}$$

$$\hat{k} = \frac{\sigma^2 e_i (e_i + d) + e_i^2 (d - 1) \alpha_i^2}{\sigma^2 (e_i + d) + e_i \alpha_i^2 (2e_i + d + 1)} \quad (42)$$

Equation (42) returns the biasing parameter for the KL estimator when $d = 1$, which is defined as follows:

$$\hat{k} = \frac{\sigma^2}{2\alpha_i^2 + \frac{\sigma^2}{e_i}} \quad (43)$$

Differentiate equation (40) with respect to d gives

$$\frac{\partial m(k, d)}{\partial d} = 2\sigma^2 \sum_{i=1}^p \frac{(e_i + d)(e_i - k)^2}{e_i (e_i + 1)^2 (e_i + k)^2} \\ - 2(e_i - k) \sum_{i=1}^p \frac{(e_i (2k - d + 1) + k(d + 1)) \alpha_i^2}{(e_i + 1)^2 (e_i + k)^2} \quad (45)$$

$$\frac{\partial m(k, d)}{\partial d} = 0, \text{ then}$$

$$\hat{d} = \frac{e_i (e_i (2k + 1) + k) \alpha_i^2 - \sigma^2 e_i (e_i - k)}{\sigma^2 (e_i - k) + e_i (k - e_i) \alpha_i^2} \quad (46)$$

Substituting k to be zero in equation (46), equation (46) returns the biasing parameter for the Liu estimator in (46)

$$\hat{d}_{liu} = \frac{\alpha_i^2 - \sigma^2}{\alpha_i^2 + \frac{\sigma^2}{e_i}} \quad (47)$$

For the purpose of simplifying the selection of the biasing parameter k and d we carry out the following:

From equation (46),

$$\hat{d} = \frac{e_i(e_i(2k+1) + k)\alpha_i^2 - \sigma^2 e_i(e_i - k)}{\sigma^2(e_i - k) + e_i(k - e_i)\alpha_i^2} > 0$$

It implies that $e_i(e_i(2k+1) + k)\alpha_i^2 - \sigma^2 e_i(e_i - k) > 0$; parameter k is obtained as follows:

$$k > \frac{e_i(\sigma^2 - \alpha_i^2)}{2e_i\alpha_i^2 + \alpha_i^2 + \sigma^2} \quad (48)$$

In this study we take the absolute value and the minimum value of equation (48). The absolute value is taken to ensure the estimate return a positive value.

$$k_p > \left| \min \left(\frac{e_i(\sigma^2 - \alpha_i^2)}{2e_i\alpha_i^2 + \alpha_i^2 + \sigma^2} \right) \right| \quad (49)$$

The steps for the practical selection of the biasing parameters are as follows.

1. Obtain $\hat{k}_p$ by replacing σ^2 and α_i^2 with their unbiased estimates.
2. Substitute $\hat{k}_p$ into equation (46) and obtain the absolute value and the minimum value.

$$\hat{d}_p = \left| \min \left(\frac{e_i(e_i(2\hat{k}_p + 1) + \hat{k}_p)\hat{\alpha}_i^2 - \hat{\sigma}^2 e_i(e_i - \hat{k}_p)}{\hat{\sigma}^2(e_i - \hat{k}_p) + \lambda_i(\hat{k}_p - e_i)\hat{\alpha}_i^2} \right) \right| \quad (50)$$

The biasing parameters for the KL estimator is obtained using the following biasing parameter:

$$\hat{k}_{\min} = \min \left[\frac{\hat{\sigma}^2}{2\hat{\alpha}_i^2 + \frac{\hat{\sigma}^2}{e_i}} \right] \quad (51)$$

The biasing parameter by Ozkale and Kaciranlar (2007) is adopted for the Liu estimator in this study.

$$\hat{d} = \min \left[\frac{\hat{\sigma}^2}{\hat{\alpha}_i^2 + \frac{\hat{\sigma}^2}{e_i}} \right] \quad (52)$$

The biasing parameter for the ridge regression estimator in this study is given by

$$\hat{k} = \frac{p\hat{\sigma}^2}{\sum_{i=1}^p \hat{\alpha}_i^2} \quad (53)$$

3. Simulation study

In this section, we compare the performances of the following estimators: the OLSE, the ridge regression estimator, Liu estimator, KL estimator, Ozkale and Kaciranlar estimator, Yang and Chang estimator and the proposed estimator through a simulation study. The simulation study was conducted using the RStudio programming language. It contains two parts (i) Simulation technique and (ii) Simulation results discussion.

The simulation design depends on factors such as sample size n , degree of collinearity ρ and the number of explanatory variable p . Following [9], the degree of collinearity among the explanatory variables are generated using the following equation:

$$x_{ij} = (1 - \rho^2)^{\frac{1}{2}} z_{ij} + \rho z_{i,p+1}, i = 1, 2, \dots, n, j = 1, 2, 3, \dots, p, \quad (54)$$

where z_{ij} are independent standard normal pseudo-random numbers and ρ represents correlation between any two explanatory variables. We consider $p = 4$, and 8 explanatory variables in the simulation and the variables are standardized. The response variable y is obtained as follows:

$$y_i = \beta_0 + \beta_1 x_{i1} + \beta_2 x_{i2} + \beta_3 x_{i3} + \dots + \beta_p x_{ip} + e_i \quad (55)$$

where $i=1, 2, \dots, 30, \dots, 50, \dots, 100, \dots, 200$, $e_i \sim N(0, \sigma^2)$. β is chosen such that $\beta' \beta = 1$ [20] and Newhouse and Oman (1971)). The MSE is computed as follows:

$$MSE(\alpha^*) = \frac{1}{5000} \sum_{i=1}^{5000} (\alpha^* - \alpha)' (\alpha^* - \alpha) \quad (56)$$

where α^* would be any of the estimators in this study. The estimator with the least MSE dominates others. The simulation results are presented in Tables 1 and 2. For a graphical representation, we also displayed the MSE values vs different values of the parameters and presented them in Fig. 1.

3.1. Simulation results discussion

We examine the effects of the different factors on the values of the MSE. It appears from Tables 1–2 and from Fig. 1, that the MSE increases as the variance and the number of explanatory variables increases, respectively when other variables are kept constant. For instance, from Table 1, when $\rho = 0.99$ and $n = 50$, the MSE increases from 9.603 to

Table 1. MSE of the estimators when $p = 4$.

Sigma	n	ρ	Estimators							
			$\hat{\alpha}$	$\hat{\alpha}(k)$	$\hat{\alpha}(d)$	$\hat{\alpha}_{KL}$	$\hat{\alpha}_{kd}$	$\hat{\alpha}(k, d)$	$\hat{\alpha}_{proposed}$	$\hat{\alpha}_{proposed}$
1	50	0.9	3.956	$\hat{k}$	$\hat{d}$	$\hat{k}_{min}$	$(\hat{k}, \hat{d})$	$(\hat{k}, \hat{d})$	$(\hat{k}_{min}, \hat{d})$	$(\hat{k}_p, \hat{d}_p)$
		0.95	4.638	0.318	0.447	0.140	0.243	0.362	0.111	0.059
		0.99	4.638	0.521	0.710	0.170	0.323	0.624	0.116	0.111
		0.999	9.603	1.907	1.384	0.615	0.519	2.480	0.179	0.399
	100	0.9	64.640	17.122	5.111	6.995	1.943	22.948	0.644	4.748
		0.95	1.231	0.137	0.174	0.092	0.124	0.146	0.084	0.017
		0.99	3.554	0.220	0.310	0.110	0.184	0.244	0.087	0.030
		0.999	5.019	0.664	0.882	0.157	0.337	0.826	0.093	0.129
	200	0.9	21.338	5.064	2.088	1.714	0.741	6.768	0.219	0.645
		0.95	1.152	0.072	0.083	0.059	0.069	0.075	0.056	0.011
		0.99	3.279	0.125	0.156	0.086	0.114	0.132	0.079	0.013
		0.999	4.016	0.385	0.567	0.119	0.261	0.452	0.084	0.062
5	50	0.9	11.761	2.531	1.465	0.759	0.509	3.318	0.146	0.372
		0.95	18.035	4.464	10.867	1.672	3.448	5.861	1.293	1.990
		0.99	33.220	8.756	17.392	3.401	5.468	11.643	2.083	5.011
		0.999	154.852	43.220	34.338	17.640	11.708	57.896	4.261	3.971
	100	0.9	1526.1	432.06	129.425	179.103	49.237	579.185	16.229	12.350
		0.95	5.720	1.566	4.236	0.480	1.434	1.984	0.445	0.290
		0.99	12.338	2.848	7.641	0.893	2.409	3.753	0.760	0.652
		0.999	48.560	13.136	22.146	4.590	6.807	17.566	2.300	8.945
	200	0.9	456.84	129.02	54.607	46.804	19.762	173.126	6.115	8.832
		0.95	3.200	0.792	2.053	0.227	0.759	0.978	0.219	0.157
		0.99	7.373	1.380	3.868	0.385	1.268	1.763	0.356	0.167
		0.999	24.405	6.109	14.124	2.075	4.190	8.082	1.396	1.451
		0.999	216.810	59.662	36.827	21.999	12.201	79.690	2.807	12.230

Table 2. MSE of the estimators when $p = 8$.

Sigma	n	ρ	Estimators							
			$\hat{\alpha}$	$\hat{\alpha}(k)$	$\hat{\alpha}(d)$	$\hat{\alpha}_{KL}$	$\hat{\alpha}_{kd}$	$\hat{\alpha}(k, d)$	$\hat{\alpha}_{proposed}$	$\hat{\alpha}_{proposed}$
1	50	0.9	6.273	$\hat{k}$	$\hat{d}$	$\hat{k}_{min}$	$(\hat{k}, \hat{d})$	$(\hat{k}, \hat{d})$	$(\hat{k}_{min}, \hat{d})$	$(\hat{k}_p, \hat{d}_p)$
		0.95	7.289	0.525	0.754	0.228	0.403	0.546	0.185	0.111
		0.99	7.289	0.829	1.166	0.265	0.518	0.875	0.185	0.151
		0.999	15.381	2.962	1.916	0.931	0.700	3.210	0.228	0.419
	100	0.9	105.843	26.494	6.981	10.442	2.713	29.040	0.741	1.539
		0.95	6.174	0.252	0.395	0.117	0.224	0.257	0.104	0.021
		0.99	6.615	0.359	0.690	0.187	0.286	0.371	0.172	0.036
		0.999	10.087	0.871	1.672	0.274	0.362	0.932	0.200	0.146
	200	0.9	49.033	6.100	2.265	6.084	0.827	6.989	0.243	0.734
		0.95	5.796	0.164	0.188	0.133	0.155	0.166	0.126	0.009
		0.99	6.000	0.279	0.348	0.190	0.251	0.283	0.141	0.010
		0.999	7.518	0.836	1.184	0.236	0.530	0.875	0.155	0.036
5	50	0.9	24.541	5.314	1.787	1.075	0.546	5.753	0.170	0.149
		0.95	30.508	7.103	18.697	2.363	5.521	7.743	1.822	2.417
		0.99	55.239	13.570	29.094	4.861	8.583	14.841	2.961	5.729
		0.999	254.712	65.714	47.887	25.761	15.621	72.013	5.441	12.747
	100	0.9	2509.207	654.713	149.564	265.615	57.679	718.474	17.014	21.284
		0.95	16.670	3.294	9.711	0.715	2.936	3.556	0.642	0.493
		0.99	27.383	6.055	17.144	1.440	4.859	6.586	1.154	0.830
		0.999	113.671	28.203	42.737	7.752	11.821	30.821	3.115	10.793
	200	0.9	1088.421	278.121	63.763	79.847	22.570	304.251	3.243	18.840
		0.95	10.553	1.700	4.663	0.331	1.612	1.818	0.316	0.254
		0.99	15.283	2.950	8.649	0.556	2.662	3.171	0.503	0.257
		0.999	53.054	12.852	29.559	2.918	8.185	13.970	1.828	1.665
		0.999	477.882	124.180	44.763	30.492	12.814	135.340	2.898	25.439

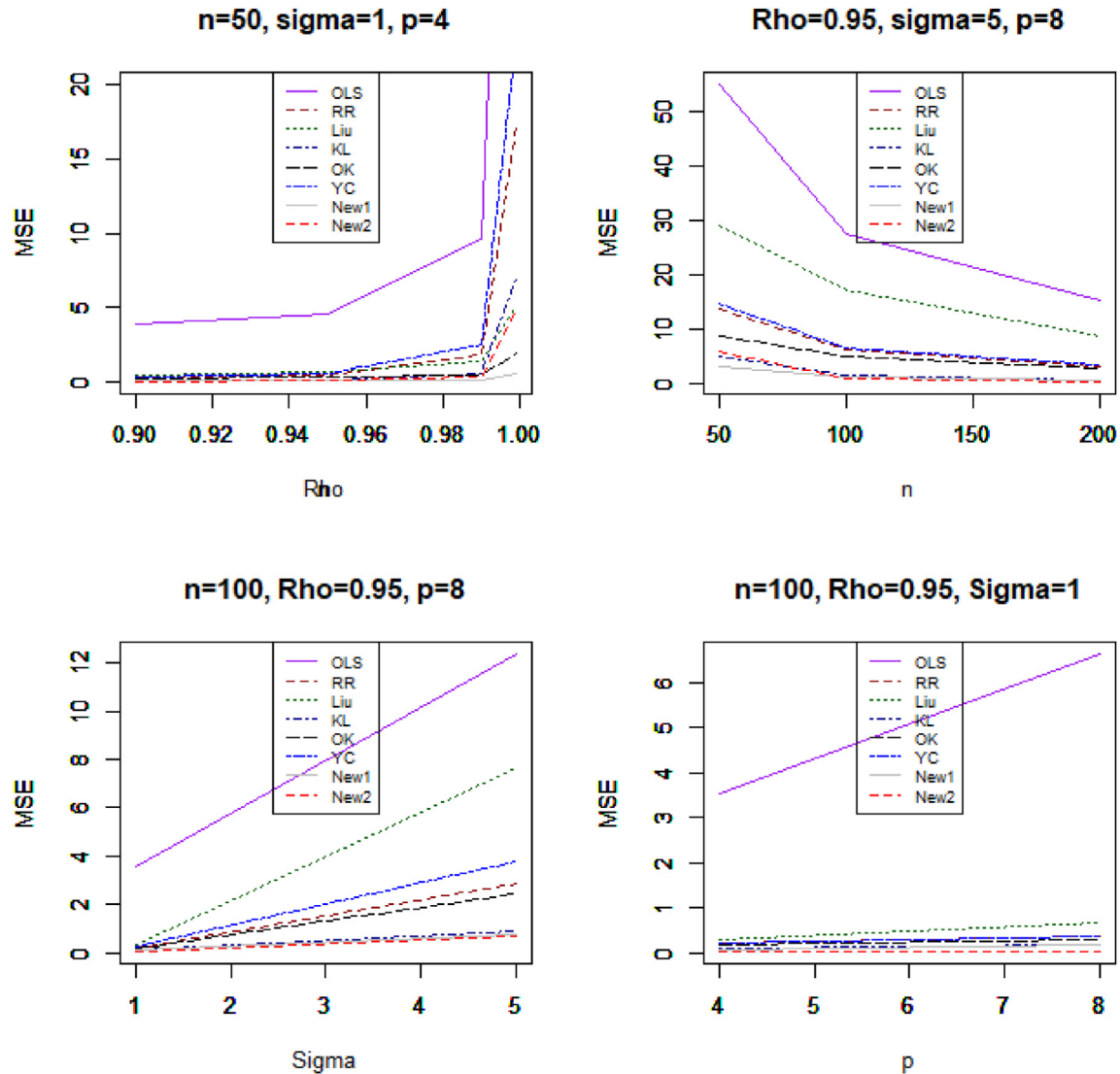


Fig. 1. : Estimated MSE values of the estimators (OLS, RR, Liu, KL, OK (Ozkale and Kaçiranlar), YC (Yang and Chang), New 1 and New 2) for different values of ρ .

154.852 as σ increases from 1 to 5. Keeping other variables constant, the MSE values of each of the estimators decrease as the sample size increases. Every other estimator considered dominates the OLSE as expected. Recall that the biased estimators considered in this study as an alternative to the OLSE can be classified into two types. Some of the estimators possess a single biasing parameter e.g. Ridge estimator, Liu estimator and the KL estimator. These estimators are called single parameter estimator while the proposed estimator, Yang and Chang estimator and Ozkale and Kaciranlar estimator exhibit two biasing parameter and are called Two-parameter estimators. From the result in Tables 1 and 2 and Fig. 1, we observed that the KL

estimator outperforms the other single parameter estimator with few exceptions when $\rho = 0.999$. Among the two-parameter estimators, $\hat{\alpha}_{proposed}$ consistently dominates. The overall performance

Table 3. Correlation coefficient among the variables.

	y	x1	x2	x3	x4	x5	x6
y	1	0.971 ^a	0.984 ^a	0.960 ^a	0.502 ^b	0.457	0.971 ^a
x ₁	0.971 ^a	1	0.992 ^a	0.979 ^a	0.621 ^b	0.465	0.991 ^a
x ₂	0.984 ^a	0.992 ^a	1	0.991 ^a	0.604 ^b	0.446	0.995 ^a
x ₃	0.960 ^a	0.979 ^a	0.991 ^a	1	0.687 ^a	0.364	0.994 ^a
x ₄	0.502 ^b	0.621 ^b	0.604 ^b	0.687 ^a	1	-0.177	0.668 ^a
x ₅	0.457	0.465	0.446	0.364	-0.177	1	0.417
x ₆	0.971 ^a	0.991 ^a	0.995 ^a	0.994 ^a	0.668 ^a	0.417	1

^a Correlation is significant at the 0.01 level (2-tailed).

^b Correlation is significant at the 0.05 level (2-tailed).

Table 4. Parameter estimation output and their MSE.

	Estimators							
	$\hat{\alpha}$	$\hat{\alpha}(k)$	$\hat{\alpha}(d)$	$\hat{\alpha}_{KL}$	$\hat{\alpha}_{kd}$	$\hat{\alpha}(k, d)$	$\hat{\alpha}_{proposed}$	$\hat{\alpha}_{proposed}$
		$\hat{k}$	$\hat{d}$	$\hat{k}_{min}$	$(\hat{k}, \hat{d})$	$(\hat{k}, \hat{d})$	$(\hat{k}_{min}, \hat{d})$	$(\hat{k}_p, \hat{d}_p)$
β_1	-52.994	1.093	-49.641	-5.041	1.253	-7.794	-4.492	-5.042
β_2	0.071	0.053	0.070	0.061	0.053	s	0.061	0.061
β_3	-0.414	-0.206	-0.408	-0.327	-0.206	-0.240	-0.325	-0.326
β_4	-0.423	-0.646	-0.432	-0.543	-0.646	-0.609	-0.544	-0.543
β_5	-0.573	-0.561	-0.574	-0.598	-0.561	-0.563	-0.599	-0.598
β_6	48.418	37.120	48.046	42.921	37.085	38.976	42.843	42.908
K		262.88		9.5524	262.88	262.88	9.3125	9.5524
D			0.1643		0.1643	0.1643	0.1643	5.06e-08
MSE	17095.15	3190.611	15182.57	2915.835	3204.145	2945.292	2916.601	2914.771

revealed that the proposed estimator outperformed all other estimators considered in this study. Furthermore, we observed that the performance of the proposed estimator is a function of its biasing parameter. The biasing parameter $(\hat{k}_p, \hat{d}_p)$ demonstrates great performance when there is severe multicollinearity when $\rho = 0.999$.

4. Example: longley data

This data was originally adopted by [16] and has been adopted by other authors in the study that involve multicollinearity (A. [37], and [18]). The model is as follows:

$$y = \beta_1 x_1 + \beta_2 x_2 + \dots + \beta_5 x_5 + \beta_6 x_6 + e \quad (62)$$

The variable descriptions are available in the references. According to Walker and Birch (1988), the condition number is 43,275 which revealed the model suffers a severe multicollinearity. The correlation coefficient is illustrated in Table 3. The result in Table 3 shows that a significant and strong positive relationship exist among the following explanatory variables: x_1 and x_2 ; x_1 and x_3 ; x_1 and x_6 ; x_2 and x_3 ; x_2 and x_6 ; x_3 and x_6 ; The variance inflation factor (VIF) of the variables are as follows: 7266.945, 1096.619, 101193.162, 42.538, 39.890 and 2365.095. Following [20], there is multicollinearity when VIF exceeds 10. The result is also evident that there is severe multicollinearity. The result in Table 4 shows that the OLSE performed least when compared with other estimators. The estimator has a very significant MSE and the results agree with the simulation study. The proposed estimator with biasing parameter $(\hat{k}_{min}, \hat{d})$ and $(\hat{k}_p, \hat{d}_p)$, and the K-L estimator performed very well by possessing the lowest MSE. The proposed estimator with biasing parameter $(\hat{k}_p, \hat{d}_p)$ dominated other estimators at some particular k and d while the K-L estimator competes favorably. The performance of the proposed agreed with the simulation result.

5. Some concluding remarks

In this paper, a new two-parameter biased estimator is proposed, and its biasing parameter were developed to circumvent the problem of multicollinearity in the linear regression set up. The properties of the new estimator are obtained, and we compared the estimator with some existing estimators theoretically. The theoretical comparison shows the proposed estimator dominate other existing estimators at some particular k and d . However, this is not sufficient and thus, it is necessary to conduct a simulation and a real-life study to further support the theoretical results. It is also evident from both results that the proposed estimator outperformed other existing estimators considered in this study. Consequently, we recommended this estimator for researchers in modelling a linear regression model with the challenge of multicollinearity. This method can also be extended to the generalized linear models.

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